

Measuring loss reserving uncertainty with machine learning models

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Gráinne McGuire

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Overview

- Introduction
- Claims reserving
- Uncertainty
- Lassoing the model set
- Bootstrapping
- Results
- Conclusion



Reference material

- Paper:
 - Model error (or Ambiguity) and its estimation with particular application to loss reserving
 - <u>https://doi.org/10.3390/risks11110185</u>, Risks 2023, 11(11), 185
- Tutorial example, including full R code:
 - Model error via regularised regression CAS monograph data
 - https://grainnemcguire.github.io/post/2023-05-04-model-error-example/





Introduction

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Take-homes

Technical approach to reserving including variability estimation

Pragmatic bootstrapping tips

Machine learning and potential to measure model error

Components of variability

Transfer ideas to other areas



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Claims reserving

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Claims reserving problem





How to estimate the reserve?



- Algorithmically / Stochastic
 - E.g. CL / BF / GLMs

What about uncertainty estimates?





Uncertainty

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Divide and conquer

Forecast error





Divide and conquer some more











External model structure error





Estimating process error with Monte Carlo simulation



For each prediction, sample from

 $f(\widehat{\mu}_i, \widehat{\sigma}_i)$



Parameter error with bootstrapping



By Biggerj1, Marsupilami - * File:Thist german.png, Autor: MM-Stathttps://postimg.cc/MffYNykZ, Autor Biggerj1, CC BY-SA 4.0, https://commons.wikimedia.org/w/index.php?curid=135426288



Model error – Bayes and model sets



Actuary's secret recipe – remove some of the pie



Some models match the past well but go off the rails in the future





Lassoing the Model set

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Bayesian lasso interpretation yields the model set

The Lasso

• Model form:

$$y = h^{-1}(X\beta) + \varepsilon$$

Loss function

 $\widehat{\boldsymbol{\beta}}(\boldsymbol{\lambda}) = \arg\min_{\boldsymbol{\beta}} [\ell(\boldsymbol{y}|\boldsymbol{\beta}) + \boldsymbol{\lambda}^T |\boldsymbol{\beta}|]$

- ℓ = negative log-likelihood (NLL)
- |. | operates elementwise on β
- λ = penalty parameter vector with non-negative components
- Model set generation
 - Each λ corresponds to a different model

Prior distribution

• Laplace prior distribution $\pi(\beta) \propto exp(-\lambda^T |\beta|)$



Specifying the prior

- Prior specification for a single parameter (excluding intercept):
 - Mean: 0
 - Variance: $Var[\beta_j] = 2/\lambda_j^2$
- All parameters (excluding intercept)
 - $\lambda^T = \lambda(1, \dots, 1)$
 - $\lambda = 0 \rightarrow ML$ solution
 - $\lambda \rightarrow Inf \rightarrow Intercept$ only model
 - What λ to use to lead to sensible model sets??



Reasonable priors

• Lambda.1se and lambda.min



- Lasso models usually fitted using cross validation (CV) to select penalty to use
- Popular choices:
 - Lambda.min = penalty corresponding to model with minimum CV error
 - Lambda.1se = penalty where CV error 1 standard error from minimum – protects against over-fitting



Extreme (but reasonable?) priors



Synthetic data sets

- Data set 1
 - Satisfies chain ladder assumptions
- Data set 2
 - Payment period effect included
- Data set 3
 - Accident development period interaction included for small number of recent cells
- Data set 4
 - Like data set 2 but payment period effect depends on development period



Internal model structure error

D-4- 0-4	LASSO Model		Loss Rese	5 (;) 10005 (0.10	
Data Set		True Forecast		Estimated IMSE (COV)	
			Raw 1se	Posterior	
		AUDB	AUDB	AUDB	96
1	Simple	190		198	0.7
	1se	190	194	194	0.4
	minCV	190		194	0.5
	Complex	190		203	0.8
2	Simple	238		260	0.1
	1se	238	261	260	0.1
	minCV	238		244	3.4
	Complex	238		272	3.1
3	Simple	608		877	1.7
	1se	608	778	777	6.8
	minCV	608		687	2.0
	Complex	608		875	5.8
4	Simple	216		244	0.2
	1se	216	247	247	0.3
	minCV	216		268	0.7
	Complex	216		276	1.2

- Model error estimated as variance over the model set
- Volatile estimates "thin" posteriors
 - -10-30 models, not a lot
- Can we enhance with bootstrapping?
 - Also allows us to estimate parameter error + process error





Bootstrapping

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Bootstrapping



Estimating uncertainty with the bootstrap





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Results

Numerical results

Data	Prior	Forecast							
set		True	Mean	Internal	Parameter	Process	Total		
		(\$B)	(\$B)	model	error (CoV)	error (CoV)	error (CoV)		
		error (CoV)							
1	1se	190	189	0.32%	5.30%	3.29%	6.24%		
	lambda.min	190	192	0.41%	5.15%	2.75%	5.85%		
2	1se	238	252	1.45%	10.00%	3.93%	10.84%		
	lambda.min	238	240	1.79%	8.83%	4.69%	10.16%		
3	1se	608	703	2.27%	11.23%	5.71%	12.80%		
	lambda.min	608	589	2.12%	11.19%	5.27%	12.54%		
4	1se	216	243	1.37%	8.63%	4.01%	9.62%		
	lambda.min	216	252	1.81%	12.54%	5.08%	13.65%		





Conclusion

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Take-homes

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Other comments

External model error



Model and parameter error are linked

Internal model error leaks into parameter error – so consider combined estimate only





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The views expressed in this presentation are those of the presenter.

